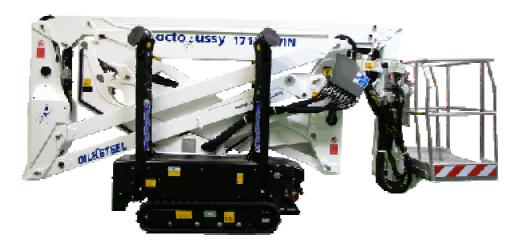
# octopussy 1715 twin



## **DESCRIPTION OF THE TECHNICAL FEATURES**

Aerial platform installed on a self-propelling tracked vehicle, designed for aerial access and work at a height where a wheeled vehicle cannot be used, i.e. steep or sandy terrain, areas that are difficult to access or with reduced dimensions (churches, museums, theatres, etc) and areas with a low concentrated specific capacity (such as floors of garages or basements).

#### **BASE FRAME**

Sheet steel structure. Tracked vehicle with rubber tread with a wide support base, driven hydraulically. The tracks have independent hydraulic traction and can be used on slopes with gradients of up to 28% in the travel direction.

#### **STABILISATION**

Stabilisation is provided by four supports that are operated by hydraulic pistons. The plate resting on the ground is connected to the lower part of the stabiliser and can move in all directions to adapt perfectly to the terrain. When at rest, the stabilisers retract completely.

### **ARM-BEARING TURRET**

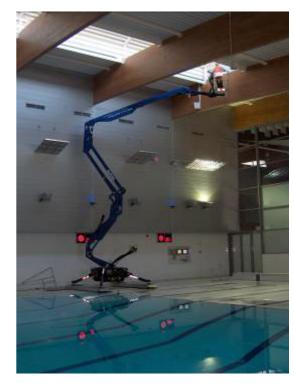
Made of high-quality sheet steel connected to a base bearing. The turret rotates driven by a rotating fifth wheel with worm screw; the unit is completely self-locking.

#### ARM

Hydraulically operated extendible telescopic arm. The extendible parts slide on plastic sliding blocks with a very low friction coefficient. The arm has an operating range of -  $0^{\circ}$  to +  $75^{\circ}$  in relation to the horizontal and is articulated to enable it to go over high ostacles. The tower is a rticulated as a pantograph and is driven by a hydraulic cylinder that enables the telescopic arm to work at a great height.

#### **OPERATORS' PLATFORM**

It is made entirely of a luminium and to provide the operators with easy access, it has a generously proportioned front opening that is guarded by a bar that shuts through the force of gravity. The platform has a rapid release that enables the space that it occupies during transit of the equipment to be minimised.





#### **PLATFORM LEVELLING**

It uses a hydraulic pantograph system that is able to rephase the horizontal condition.

#### **CONTROLS**

Hydraulic, with a dual position: on platform and on turret. The commands and controls for the engine are located on the ground frame. The translation and stabilisation operations are controlled by a double hydraulic distributor with independent operation. The control distributors of the arm have sensitive proportional levers. The electric power panel is located in the platform control position and comprises the various consent and alarm warning lamps, and the motor starter switch From this position the platform can be levelled manually. The self-retaining emergency and engine stop switch is located in all the command and control positions.

## STANDARD SAFETY DEVICES

- Hooks for safety belts
- Fixing attchements on the frame of the machine during conveying
- Device on self-locking rotation
- Arm/drive motion interlock
- 4 fixtures on stabilizers to move machine by lifting equipment
- Manual pump for emergency descent
- Thermal overload protection on electrical system
- Drive-motion intermittent acoustic alarm
- Max. valve on hydraulic circuit
- Stop valves on all cylinders

## **SERIALLY MOUNTED ACCESSORIES**

- Main motor and any auxiliary motor switched on and off from the
- Removable platform-reduction of front profile down to 78 cm by mechanical removal of operators' platform
- 2 safety belts
- Machine operation hour counter
- 220VAC, 2.2kw monophase electric pump comprising an electric control panel and battery charger supplied from an external network.
- 220 VDC monophase electric power takeoff on platform with differential switches
- Drive motion acoustic warning
- Lamp indicating centring of rotation of turret on platform
- Luminous position indicators installed on stabilizer arms







## **FEATURES AND PERFORMANCE**

Angular outreach of telescropic arm

**Stabilizers** 

Platform lowering Operating arm Arm angle Pantograph

Pantograph angle Arm articulations

Max. drive-motion speed Enlargeable rubber tracks

Traction Max. incline Length

Width (without platform)

Height

Max. operating height Max. operating outreach

Capacity

**Number of operators** 

Dimensions of aluminium removable operator platform

Controls Turret rotation Engine

Running weight

From  $0^{\circ}$  to  $+75^{\circ}$ 

Overturnable and lowered hydraulically

Hydraulic in closed circuit Telescopic in two sections, steel

0°/+75°

-20°/+60°

Double bar, steel

2 + telescopic 1.2km/h 180x34x72 Hydraulic 28% 4,395 mm 780 mm 2,020 mm

17.00 m/1 operator - 15.20 m/2 operators 6.80 m/1 operator - 5.2 m/2 operators

120-200 kg/1 operator

1-2

1400 x 700 xh 1100 mm

Hydraulic 350°

One-cylinder Honda 1850 kg 1980

## **OPTIONALS AVAILABLE ON REQUEST**

- Pair of white trace tapes for internal use
- Inclinometer with acoustic a larm that is set off when permitted incline is exceeded
- Multiuse power line to platform
- Enlarged plates in nylatron, d. 300
- Adhesive messages on arm
- Paint other than standard (white RAL 9016)

## **OPERATING AREA AND GEOMETRICAL FIGURES**

